

ABSTRACT OF THE DISCLOSURE

A DC motor control method and apparatus for
reducing time required for deceleration without
degrading positioning accuracy. In a device which drives
5 a mechanism by using a DC motor as a power source, in
deceleration of the DC motor, when the mechanism arrives
at a predetermined position, a velocity command value to
the motor, generated in accordance with a cubic function
having a mild curve profile, is changed to a constant
10 value, thus the velocity is discontinuously reduced.

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